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Recent Advances in Manufacturing of Riblets on Compressor Blades and Their Aerodynamic Impact

Since Oehlert et al. (2007, "Exploratory Experiments on Machined Riblets for 2-D Compressor Blades," *Proceedings of International Mechanical Engineering Conference and Exposition 2007, Seattle, WA, IMECE 2007 – 43457.*), significant improvements in the manufacturing processes of riblets by laser structuring and grinding have been achieved. In the present study, strategies for manufacturing small-scale grooves with a spacing smaller than 40 μm by metal bonded grinding wheels are presented. For the laser-structuring process, significant improvements of the production time by applying diffractive optical elements were achieved. Finally, strategies for evaluating the geometrical quality of the small-scale surface structures are shown and results obtained with two different measuring techniques (SEM and confocal microscope) are compared with each other. The aerodynamic impact of the different manufacturing processes is investigated based upon skin friction reduction data obtained on flat plates as well as the profile-loss reduction of riblet-structured compressor blades measured in a linear cascade wind tunnel. Numerical simulations with MISES embedded in a Monte Carlo simulation (MCS) were performed in order to calculate the profile-loss reduction of a blade structured by grinding to define further improvements of the riblet-geometry. A numerical as well as experimental study quantifying the relevant geometrical parameters indicate how further improvements from the present 4% reduction in skin friction can be achieved by an additional decrease of the riblet tip diameter and a more trapezoidal shape of the groove in order to realize the 8% potential reduction. [DOI: 10.1115/1.4007590]

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6 Introduction

7 A major goal in turbomachinery design is the increase of
 8 efficiency in order to reduce the fuel consumption of aircraft
 9 engines or gas turbines and, hence, the operating costs and CO₂-
 10 emissions. To attain an increase of efficiency, the flow losses must
 11 be reduced. Approximately 50% of the losses are generated by the
 12 secondary flows (Gümmel [1]). Thus, approximately 50% of
 13 the losses are generated by the blading with a dominant portion
 14 of the friction losses, especially in the turbulent boundary layer of
 15 compressor blades with an early onset of boundary layer transition
 16 near the leading edges. Therefore, a decrease of skin friction leads
 17 to an additional increase in efficiency.

18 It is known that small ribs on the surface, oriented in the mean
 19 flow direction, can reduce skin friction in the case of turbulent
 20 boundary layer flow when their geometric properties are appropriate
 21 to the local flow conditions. These ribs, also known as riblets,
 22 are, therefore, a passive control mechanism to reduce drag and
 23 can also be found in nature on the skin of fast swimming sharks
 24 (Reif et al. [2]). The drag reduction mechanism can be related to
 25 an interaction of riblets with the streaky structures in the viscous
 26 sublayer. Riblets oriented into the mean flow direction can hamper
 27 the cross flow of the streak structures at the wall. Hence, the vertical
 28 motions of the fluid and the turbulent shear stresses are
 29 reduced. The streak structures are moved away from the surface
 30 and are primarily in contact with the riblet tips.

31 Idealized geometries with less complexity in comparison to the
 32 shark skin were first investigated on flat plates by Walsh [3] at
 33 NASA Langley Research Center. Later, in the 1990s, extensive
 34 experimental investigations on the effect of various 2D riblet
 35 geometries on the skin friction of flat plates were carried out by
 36 Bechert et al. [4] in the oil channel of the Institute of Propulsion
 37 Technology of the German Aerospace Center (DLR) in Berlin.
 38 The experiments were confined to flows with zero pressure gradients.
 39 The best drag reduction, up to 10%, was achieved by
 40 blade-type ribs. Unfortunately, the structural strength of this type
 41 of geometry is expected to be insufficient under operating conditions
 42 of aircraft engines or gas turbines. A good compromise
 43 between structural strength and drag-reduction potential is
 44 achieved, for instance, by riblets with a trapezoidal or triangular
 45 groove.

46 With these types of riblets, a few experiments were carried out
 47 by different research groups in order to investigate their potential
 48 to reduce profile losses of compressor blades. A brief overview of
 49 the results obtained by different research groups is given in
 50 Oehlert and Seume [5]. Most of these investigations involved the
 51 application of foils carrying small ribs with ideal groove geometries
 52 and sharp tips to the surface of the compressor blades. This
 53 application technique is neither suitable for industrial nor aircraft
 54 gas turbine engine blading, as the foil is expected to be of insufficient
 55 mechanical strength under the operating conditions of these
 56 engines.

57 Ideally, the riblets should be manufactured in the bulk material
 58 of the turbine or compressor blade on the same machine tool as
 59 is used to machine the airfoil shapes of the blade in order to
 60 avoid additional setup times. This leads to the main objective, the
 61 manufacturing of riblets by means of applicable industrial manufacturing
 62 processes, and is the motivation of the research project

“riblets for compressor blades” funded by the German Research
 Foundation (DFG). 63

64 As shown by Oehlert and Seume [5] and by Oehlert et al. [6],
 65 the initial investigations of riblets created on compressor blades
 66 by means of industrial manufacturing processes were very promising.
 67 The surface structures were produced on the compressor
 68 blades by grinding (IFW) and laser structuring (LZH) as described
 69 by Denkena et al. [7] and Siegel et al. [8]. An optimization of the
 70 riblet application method by Lietmeyer et al. [9], resulting in an
 71 additional reduction of profile loss, involved the adaptation of the
 72 riblets to the local flow conditions and the selective placement of
 73 the riblets on the blade surfaces. 74

75 The present paper presents recent improvements in grinding
 76 and laser-structuring techniques for accurate geometric production
 77 of riblets on compressor blades and the reduction of production
 78 times. Measuring techniques for the evaluation of the geometry of
 79 small-scale structures and, finally, a methodology for assessing
 80 the aerodynamic impact of riblet geometry on compressor blade
 81 profile losses are presented.

Recent Advances in Manufacturing of Riblets by Grinding

82 Grinding with multiprofiled wheels has been established as an
 83 effective method for generating riblet structures on large-scale
 84 surfaces. Vitrified bonded grinding wheels can be used to generate
 85 microgroove structures with a width of 26 μm to 120 μm (Fig. 1).
 86 In order to utilize the full potential of riblet structures with a trapezoidal
 87 groove, it is necessary to generate microprofiles with an
 88 aspect ratio of riblet height to spacing of $h/s=0.5$. The ground
 89 riblet structures with a spacing of 26 μm, however, did not reach
 90 the required aspect ratio and since a riblet spacing as small as
 91 20 μm (with a height of 10 μm) is required for compressor blade
 92 applications, the grain size of the abrasive material must be down-
 93 scaled in order to achieve the required geometries. However, if
 94 the grain size is too small, the bonding forces will decrease and
 95 the grinding wheel wear will increase (Denkena et al. [7]). In
 96 order to reduce tool wear and the dimensional limit inherent in the
 97 production of riblet geometries by means of vitrified bonded
 98 grinding wheels, metal bonded grinding wheels can be used. Due
 99 to the high bonding forces of the metal binding, small grain sizes
 100 can be used without an increase of the tool wear (Klocke et al.
 101 [10]). In contrast to vitrified bonding, however, metal bonded
 102 grinding tools are difficult to dress by conventional dressing
 103 methods. 104

105 In principle, electronic contact discharge dressing (ECDD) is
 106 suitable for generating complex profiles on metal bonded wheels
 107 (Denkena et al. [11], Zaeh et al. [12]). Here, one pole of the direct
 108 current circuit is connected to an electrode and the other pole is
 109 connected to the steel body of the grinding tool by carbon brushes.
 110 During dressing chips are generated from the electrode, which
 111 establish a distortion of the electric field between the electrode
 112 and the metal bond. An arc-over is the result of the increasing
 113 field distortion and the chip is vaporized. The thermal energy
 114 released in this process melts and removes the bond material
 115 locally. The dressing strategy is shown in Fig. 2. The electrode (a
 116 copper wire with a diameter of 1 mm) moves radially to the
 117

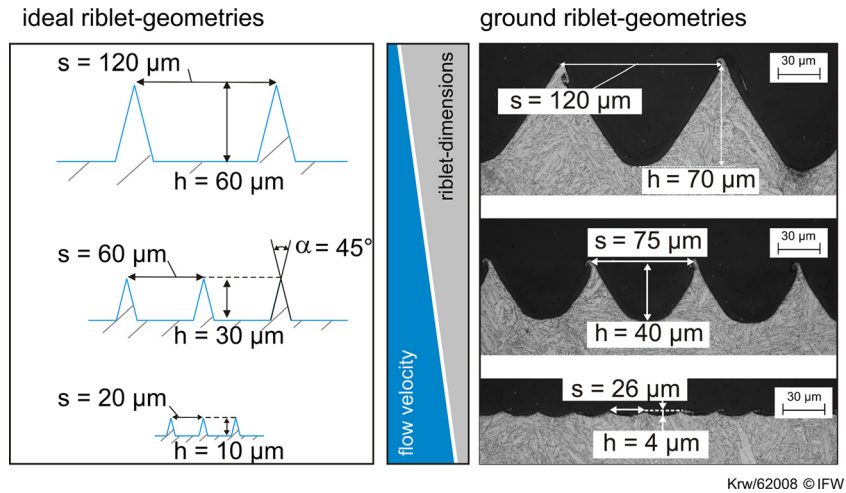


Fig. 1 Riblet geometries ground by vitrified bonded grinding wheels

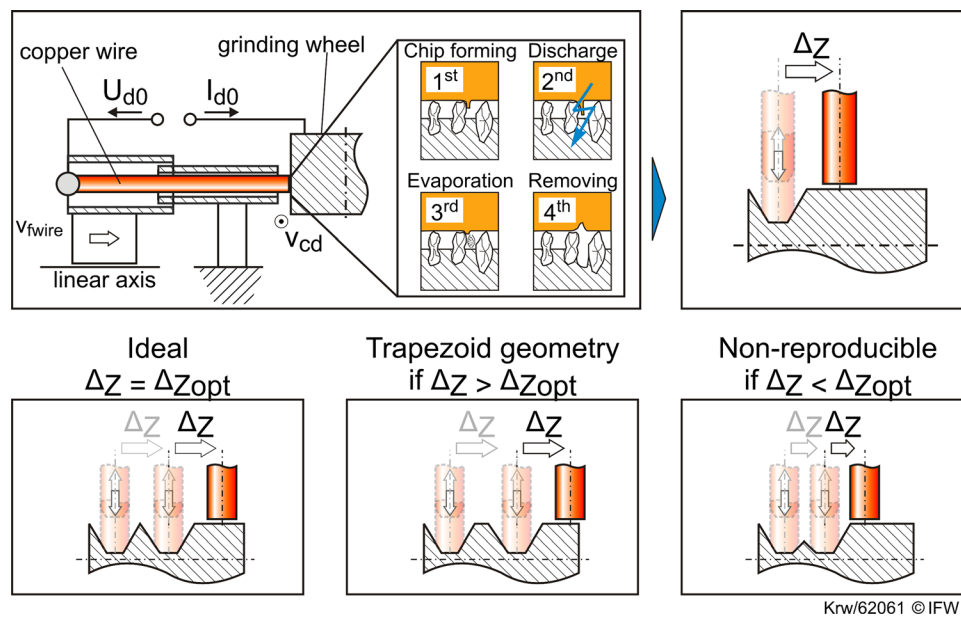


Fig. 2 ECDD-strategy

118 grinding wheel and generates a trapezoidal groove (Fig. 2). In a
 119 second step, the wire is displaced about Δz and then moved radi-
 120 ally again. Using this strategy, a number of profiles can be created
 121 on the grinding wheel. The spacing of the dressed profiles on the
 122 grinding wheel is larger than the riblet spacing (Fig. 3). However,
 123 a riblet spacing smaller than the profiles on the grinding wheel
 124 is generated on compressor blades by a shift strategy (Denkena
 125 et al. [7]).

126 The displacement Δz is varied to find Δz_{opt} which generates the
 127 smallest profile geometries on the grinding wheel. The profile
 128 geometries, including the profile heights, are evaluated at a profile
 129 width of $20 \mu\text{m}$ and $60 \mu\text{m}$ (h_{20} and h_{60}). Trapezoidal profiles will
 130 be generated if Δz is too big. In the case of smaller Δz , the height
 131 of the microprofiles on the grinding wheel is reduced by an over-
 132 lap. This means the smallest profiles will be produced if the
 133 dressed geometries just touch each other. In this study grinding
 134 wheels (MB6.3 and MB10, Fig. 3) with two different grain sizes
 135 ($6.3 \mu\text{m}$ and $10 \mu\text{m}$) were utilized. The optimal displacement Δz_{opt}
 136 for the grinding wheel MB10 was 1.035 mm . The minimum size
 137 profiles on grinding wheels with a grain size of $6.3 \mu\text{m}$ were gen-
 138 erated at a Δz_{opt} of 1.025 mm . The displacement Δz_{opt} is depend-
 139 ent on the grain size due to the dressed groove width. During the

dressing process, the metal bonding melts, grains fall out, and a
 groove is generated. If a grain with a size of $10 \mu\text{m}$ falls out, the
 width of the roof will increase about $10 \mu\text{m}$. The increase will be
 less for smaller grain sizes.

In order to grind riblet structures with a riblet spacing of
 $20 \mu\text{m}$ and an aspect ratio of $h/s = 0.5$, the grinding wheel profile
 should have a height h_{20} of nearly $10 \mu\text{m}$. By applying the metal
 bonded grinding wheel MB10, a profile height of $32 \mu\text{m}$ was
 reached at a profile width of $60 \mu\text{m}$. A profile height h_{20} could
 not be measured due to the low sharpness of the profiles. The
 SEM view shows that there was only one grain on the tip of the
 grinding wheel profile. As a result, it is not possible to dress
 smaller profile geometries by applying grinding wheels with a
 grain size of $10 \mu\text{m}$. Compared to the grinding wheel MB10, the
 profile height h_{60} of the grinding wheel MB6.3 increased about
 100% to $72 \mu\text{m}$. In addition, both results show that the profile
 geometries were generated with a high reproducibility (Fig. 3).
 The minimum possible profile geometry is dependent on the
 grain size due to the fact that at least one grain must be at the
 peak of the profile. The bigger the grain the bigger the profile
 geometry. In addition, a great number of grains on the peak of a
 profile add stability to the peak.

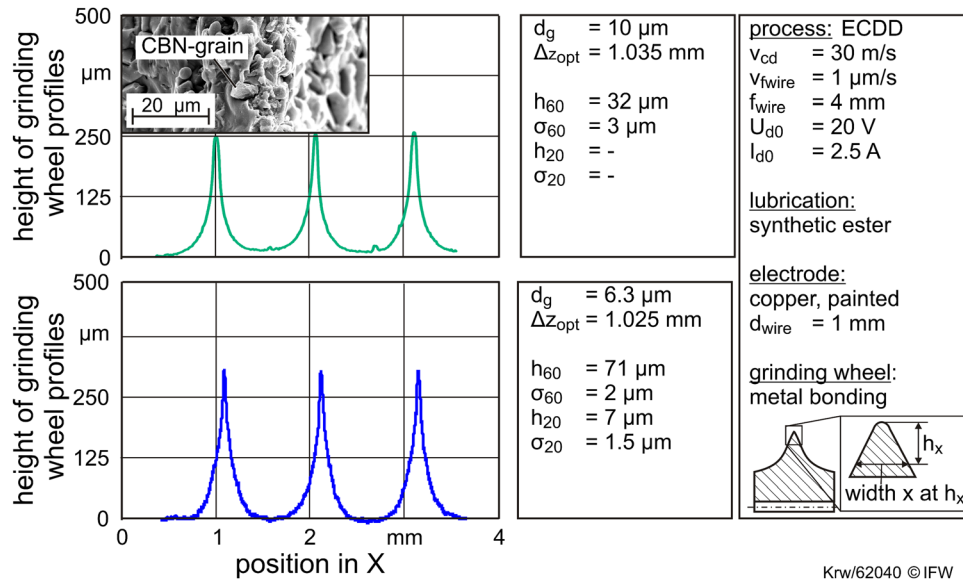


Fig. 3 Microprofiles on the grinding wheel

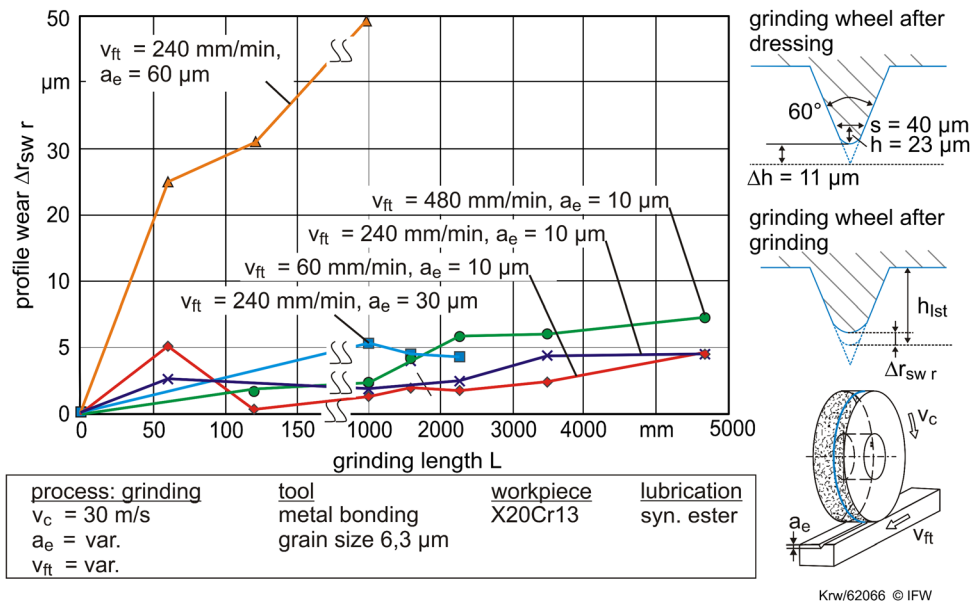


Fig. 4 Wear behavior over the grinding length for different v_t and a_e

162 ECDD is a time consuming dressing method. In order to dress
 163 grooves with a depth of nearly $250\ \mu\text{m}$, a copper wire infeed of
 164 $4\ \text{mm}$ is required. Since the wire moves at a feed rate of $1\ \mu\text{m}$ per
 165 second, $264\ \text{min}$ are required to dress three profiles on a grinding
 166 wheel. An economical use of metal bonded grinding wheels is
 167 possible if the grinding wheels have a low wear rate.
 168 The wear characteristics of metal bonded grinding wheels were,
 169 thus, analyzed as part of the present study. The radial wheel profile
 170 wear $\Delta r_{sw,r}$ was evaluated for different depths of cut a_e and
 171 feed rates v_{ft} during the grinding of a typical steel material for
 172 compressor blades, X20Cr13 (St1.4021). A nearly linear wear
 173 behavior across the grinding length L is depicted in Fig. 4. In contrast
 174 to the wear of vitrified bonded grinding wheels, metal bonded
 175 grinding wheels had a much lower wear rate. A vitrified bonded
 176 SiC-grinding wheel at a feed rate of $240\ \text{mm/min}$ and a depth of
 177 cut of $30\ \mu\text{m}$ showed a profile wear of $30\ \mu\text{m}$ after a grinding
 178 length of $2000\ \text{mm}$ (Klocke et al. [10]). A metal bonded tool had a
 179 profile wear of just $5\ \mu\text{m}$ for the same process parameters.

The variation of the feed rate between $60\ \text{mm/min}$ and $480\ \text{mm/min}$ at a constant depth of cut had just a minor influence on the profile wear. This behavior suggests that the mechanical loads, which increase with increasing feed rates, do not affect the tool wear. The tool wear is mainly dependent on the depth of cut. At a grinding length of $1000\ \text{mm}$, the radial profile wear at a depth of cut of $60\ \mu\text{m}$ is much higher than that for a depth of cut of $30\ \mu\text{m}$. The increase of the depth of cut raises the contact length between the grinding wheel and the workpiece. A long contact length reduces the supply of lubricant and impedes the removal of chips. The lack of lubricant increases the friction between the grinding wheel and the workpiece. Furthermore, as the chips clog the grinding wheel topography, the grinding effectiveness of the abrasive grains is reduced; thus increasing the thermal loads on the grinding wheel. As a consequence, the thermal loads can increase the profile wear. The supply of lubricant can be improved by using grinding wheels with a larger grain size, but these profiles did not reach the required profile geometries after dressing.

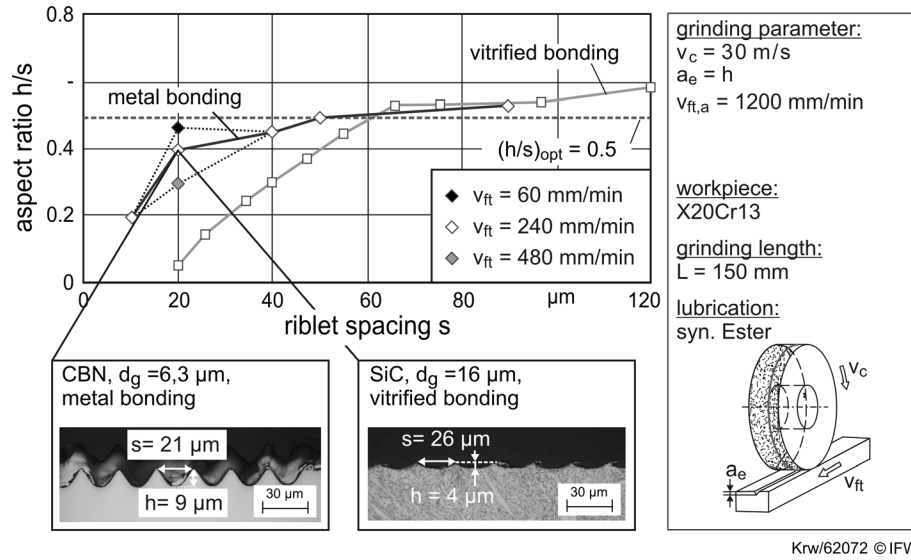


Fig. 5 Aspect ratio of ground riblets

198 With the metal bonded grinding wheel riblets were generated
 199 with a depth of $9\ \mu\text{m}$ and a width of $21\ \mu\text{m}$ and, hence, an aspect
 200 ratio of $h/s \approx 0.5$. Such an aspect ratio cannot be attained with
 201 vitrified bonded grinding wheels. Nevertheless, the wear of metal
 202 bonded grinding wheels at a depth of cut of about $60\ \mu\text{m}$ is unac-
 203 ceptably high (Fig. 5).

204 Consequently, vitrified and metal bonded grinding wheels have
 205 different areas of application. Whereas metal bonded grinding
 206 wheels can be used for the manufacturing of small riblet geome-
 207 tries with a riblet height of $10\ \mu\text{m}$, vitrified bonded grinding
 208 wheels should be used for the grinding of riblet structures with a
 209 height of more than $30\ \mu\text{m}$.

210 **Recent Advances in Manufacturing of Riblets by Laser**
 211 **Structuring**

212 As shown in Ref. [6], the production of riblets using short
 213 pulsed laser radiation in the pulse length regime of several pico-
 214 seconds yields very good machining results. The flexibility of
 215 laser machining is especially valuable since variable riblet spacing
 216 can be easily achieved by simple on-the-fly modification of the
 217 machining parameters. A schematic of a laser machining setup is
 218 shown in Fig. 6.

219 Using the shown processing method, an area processing rate of
 220 $0.1\ \text{mm}^2/\text{s}$ can be achieved. This speed can be increased signifi-
 221 cantly by using optical components to split the laser beam into

222 multiples without changing the relevant beam characteristics [13].
 223 Therefore, the available laser power can be fully exploited,
 224 whereas with a single beam setup the maximum applicable power
 225 is limited by the ablation regime, where pulse energies above
 226 $7\ \mu\text{J}$ – $35\ \mu\text{J}$ cause thermal ablation and insufficient machining
 227 results [14]. On modern lasers, pulse energies of $125\ \mu\text{J}$ are readily
 228 available; thus, using an appropriate optical setup, a speed
 229 increase up to a factor of 17 is possible depending on the riblet
 230 geometry.

231 Parallel processing is achieved by augmenting the single beam
 232 setup with an additional diffractive optical element (DOE) for
 233 beam splitting purposes, which is put into the beam between the
 234 beam expander and scanner. Since the beam distances in the
 235 focal plane are fixed, dynamic rotation of the DOE is used to
 236 change the laser spot distance in relation to the scanning direction
 237 (Fig. 7).

238 The fan of laser spots created by the DOE enables the parallel
 239 machining of riblets along the entire blade length. This is done
 240 by scanning hatched rectangles with a width of the spot-to-spot
 241 distance and a hatch distance of the riblet width (Fig. 8). The
 242 point-to-point width for every riblet geometry has to be matched
 243 for an even overall width to avoid curved outlines that would
 244 cause nonmachined areas [15].

245 So far, an increase in speed by a factor of five was achieved
 246 ($0.5\ \text{mm}^2/\text{s}$ versus $0.1\ \text{mm}^2/\text{s}$ effective scan speed) using a seven
 247 spot DOE. An asymptotical closure by a factor of seven seems
 248 highly probable using electro optical switches instead of the
 249 mechanical ones used in our experimental setup. The ablation
 250 quality is equal to single-spot machining and especially improved

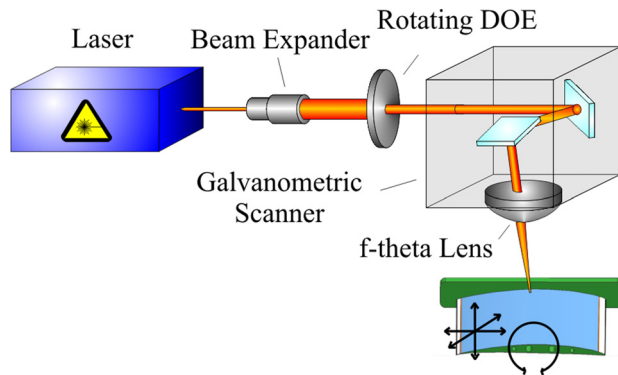


Fig. 6 Principal setup for laser machining. The multi-axis translation system positions the area of interest of the blades into the focal plane of the lens, while the scanner deflects the laser beam at high speed.

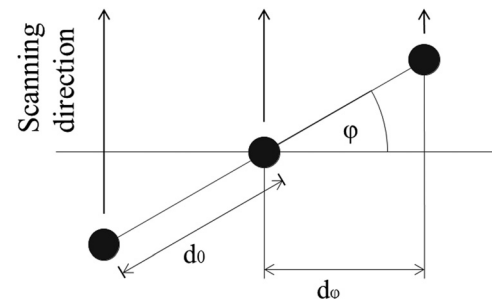


Fig. 7 Principle of three spot ablation using beam splitting DOE; the effective spot-to-spot distance is determined by the rotation angle of the DOE

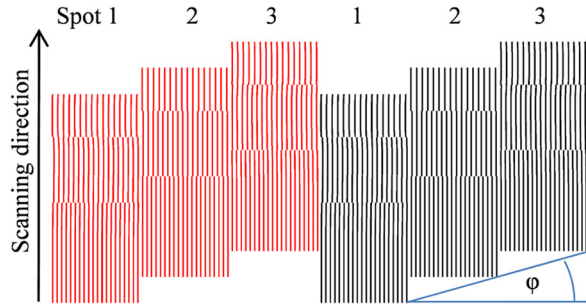


Fig. 8 Simulated lanewise scanning pattern using a three spot DOE: Two lanes are set side by side using three different riblet spacings (from top to bottom).

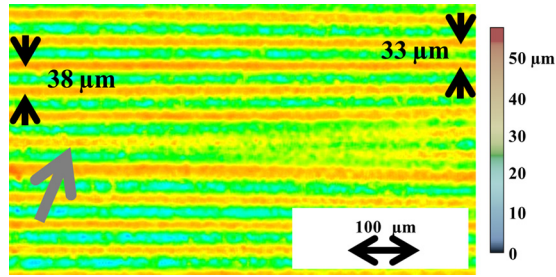


Fig. 9 Magnified confocal microscope image of a smooth parameter set transition from 38 μm to 33 μm riblet spacings. The grey arrow marks a beginning bifurcation.

251 in parameter transition zones, where sudden breaks are smoothed
 252 and bifurcations of lower frequency riblets occur (Fig. 9). This
 253 brings laser machining of riblets closer to industrial applicability.

254 Geometrical Measurement of Riblets

255 **Theory: Physical Limitations of the Measurement Principle.**
 256 All optical measurement instruments are characterized by the
 257 limited lateral resolution that is often defined as

$$d_{\min} = 0,61 \frac{\lambda}{NA} \quad (1)$$

258 with the wavelength λ of the used light. Since the numerical aper-
 259 ture (NA) of lenses used in air is less than 1, the lateral resolution
 260 is limited to approximately 200 nm. Another problem is the lim-
 261 ited capability to detect inclined surfaces. The more a surface is
 262 tilted, the less light will be reflected into the measurement lens.

Table 1 System characteristics of the confocal microscope

Magnification	20	50	100
Working distance (mm)	3.1	0.66	0.34
Measurement area (μm^2)	800×772	320×308.8	160×154.4
NA	0.46	0.8	0.95
Max. theoretic slope angle (deg)	17.7	26.6	35.5
Lateral resolution (μm)	0.78	0.34	0.2

After reaching the critical angle (approximately 36 deg), the signal
 263 becomes too degraded for a reliable surface detection. Undetected
 264 points are interpolated to counteract this effect, which sometimes
 265 leads to inaccurate results. 266

Limited adaptability of optic methods is demonstrated in
 267 Fig. 10. The intensity distribution of the cutting line is shown in
 268 the two image stacks. In the sample processed with the laser (left),
 269 the flank is clearly recognizable due to a rough surface. The foil
 270 surface (right), in contrast, hardly gives any signal; therefore, only
 271 the bottom and the highest points are recognizable. 272

A μSurf Nanofocus confocal microscope with three objective
 273 lenses was used for imaging the riblet structures. The microscope
 274 characteristics are summarized in Table 1. 275

Choice of Measurement Lenses. In theory, a lens with
 276 100 \times magnification is best suited for the measurement. However,
 277 100 \times lenses have a severe disadvantage: The measurement area is
 278 limited to ca. $160 \times 160 \mu\text{m}$. As the riblets have a typical spacing
 279 of 40–80 μm , the measurement only contains 4–2 riblet periods.
 280 Such a small area is not suitable for a statistically significant
 281 characterization of the riblet-geometry and, therefore, has to be
 282 enlarged by capturing the surface in small patches. These patches
 283 are normally merged by a correlation method (the so called stitch-
 284 ing process). Since the stitching of measured data with many sur-
 285 face defects does not always work properly, the 100 \times lens is not
 286 the best solution. A smaller magnification has to be chosen to
 287 enlarge the captured area. It was determined experimentally that
 288 the use of the 20 \times lens results in errors in the detection of the tip
 289 radii due to poor lateral resolution and the riblet profile was not
 290 reproduced accurately due to optical artifacts such as bat-wings.
 291 Therefore, the use of the 20 \times lens is not recommended for riblet
 292 analysis. The 50 \times lens was chosen because it provides the best
 293 compromise between lateral resolution and measurement area
 294 even though the measurement results differ from those obtained
 295 using the 100 \times lens, which shows slightly more accurate results
 296 because of the higher lateral resolution. This effect is also
 297 depicted in the histograms (Fig. 14). 298

Interpolation of Surface Defects. Due to the steep flank angle
 299 of the riblet structures, the information in the area of the flanks
 300

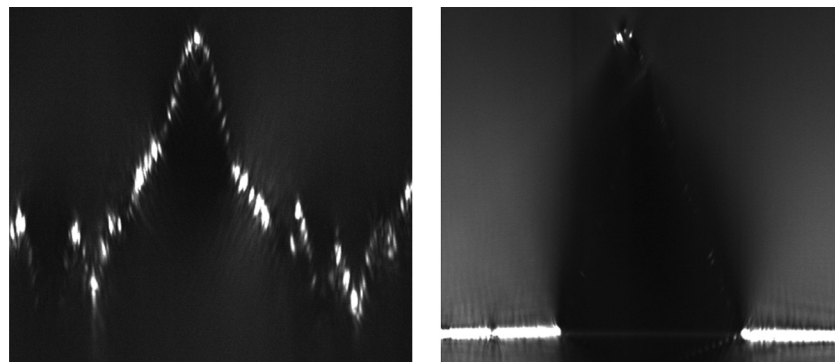


Fig. 10 Intensity distribution through the image stack for different samples

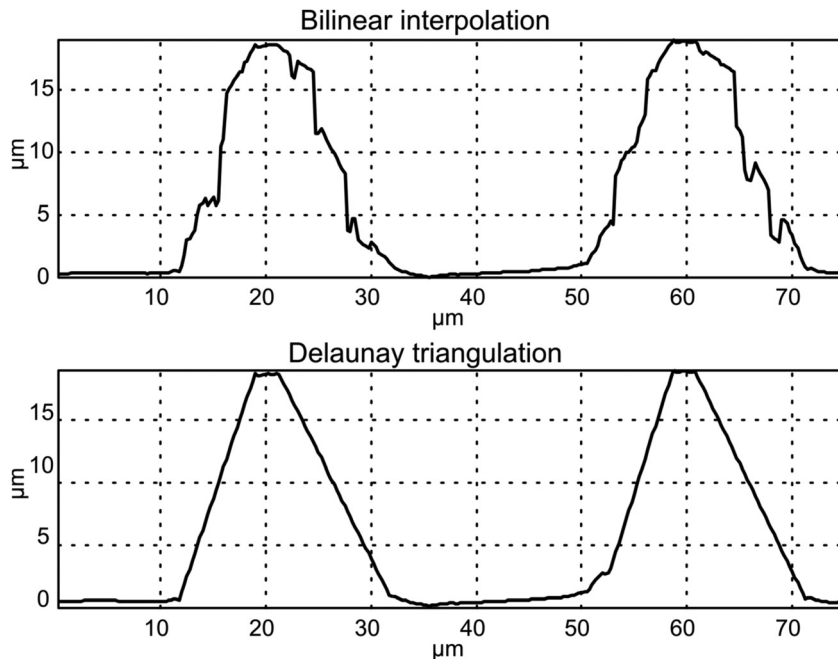


Fig. 11 Results of bilinear interpolation (top) and interpolation based on Delaunay triangulation

301 must be estimated by interpolation. Typically, bilinear interpolation is utilized, but investigations of nearly ideal riblet structures (especially when using lenses with 50× and 100× magnification) indicated that bilinear interpolation results in a significantly inaccurate indication of surface deformation (Fig. 11). Hence, the triangle-based cubic interpolation was used instead of the bilinear interpolation. The basic triangles are defined with the help of Delaunay triangulation. A result of the interpolation is depicted in Fig. 11.

310 **Calculation of Main Parameters.** The aerodynamic performance of the riblets is a function of their spacing, height and tip radius. These parameters are measured using the following methodology.

314 **Riblet Spacing and Height.** The spacing of the riblets produced by grinding and laser structuring varies over the surface. In order to define this variation, the calculation of the riblet spacing is performed locally over a small region within the overall measured area. This region is moved along the whole surface, and at each position, the significant parameters are calculated as shown in step two.

321 (1) *Region preprocessing.* The region described in step 1 has to be large enough to contain at least two complete riblet periods. Since the riblets are periodic structures, they can be approximated with dominant and harmonic waves using fast Fourier transformation (FFT). In order to obtain correct results from the FFT, the examined region has to contain whole-numbered amounts of riblet waves. If the requirements are not met, the so-called leakage effect will occur and the structures are approximated by waves of incorrect frequencies. Because the period length is not known a priori, this condition is not met generally, and therefore, the region will be cut out using zero-padding technique (Vynnyk [16]).

332 (2) *Region analysis.* The following steps are performed after preprocessing the selected region as described in step 1:

- 334 (a) FFT for preprocessed region
- 335 (b) Simplification of the spectrum (all frequencies except the dominant wave and their three harmonics are set to zero)
- 336 (c) Inverse FFT.

A result of such “simplification” of a complex manufactured surface structure is shown in Fig. 12.

Tip Radii. Contrary to the spacing and height of the riblets, the tip radii are not integral characteristics, but describe a local behavior of the surface. Therefore, the FFT cannot be applied to evaluate the tip radii and the following steps should be performed:

- (1) One period is extracted using the region analysis.
- (2) The upper 5% of the profile data is cut off from the rest. These data describe the actual tip area of the riblet as shown in Fig. 13.
- (3) A third order polynomial fit is performed from which the peak point is obtained.
- (4) If the radius of curvature at the peak of the third order polynomial fit obtained in step 3 is less than the width of the 5% “profile tip” obtained in step 2, it is assumed to be the riblet tip radius.

Verification of the Tip Radii With the SEM. As shown in the histograms (Fig. 14), the calculated tip radii depend on the lens used for making the measurements. In order to clear the impreciseness, a scanning electron microscope (DSM 940 A) with a two detector system and an image-acquisition unit from Point Electronics was used to verify the riblet tip radii.

A typical SEM-picture of a foil sample is shown in Fig. 15. The bright areas represent the riblet flanks, whereas the dark areas denote the horizontal areas. A cut through the picture gives a profile as seen in Fig. 15.

The tip width can be considered to be the distance between the highest negative and positive inclination of the intensity distribution. The flank angle should also be accounted for in the calculation of the tip radius. However, in order to maintain compatibility with the optical measured data, the influence of the flank angle is neglected and the tip radius is defined as follows:

$$r = t/2 \tag{2}$$

The SEM measurements of the tip radius correspond to the measurements made with the confocal microscope and the 50× magnification lens within 20% in all cases.

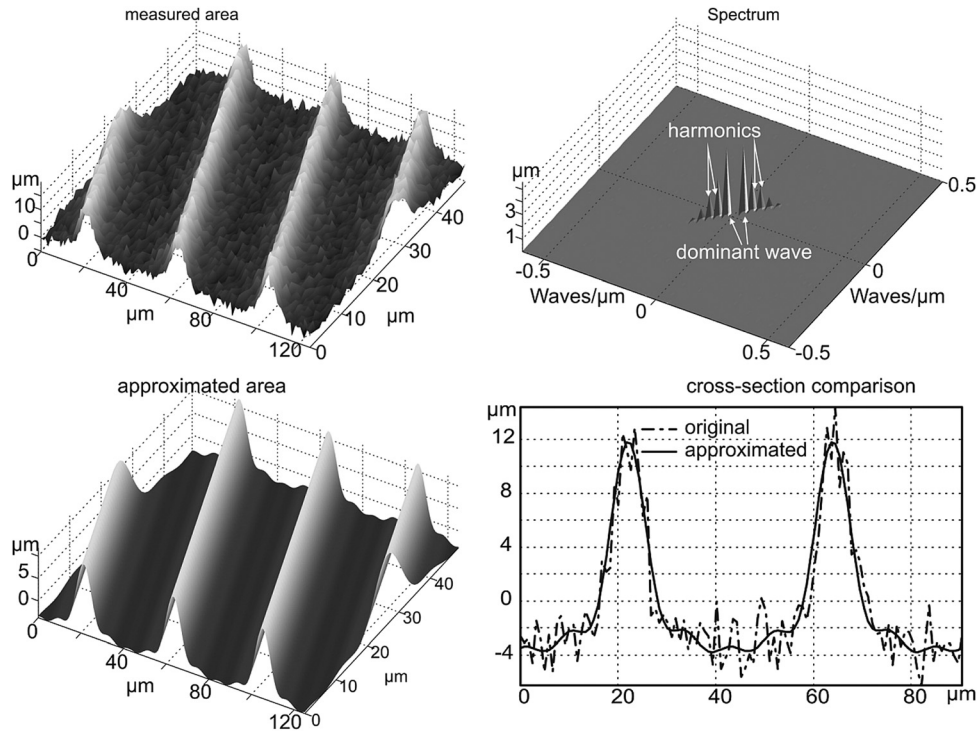


Fig. 12 Elimination of the stochastic parts

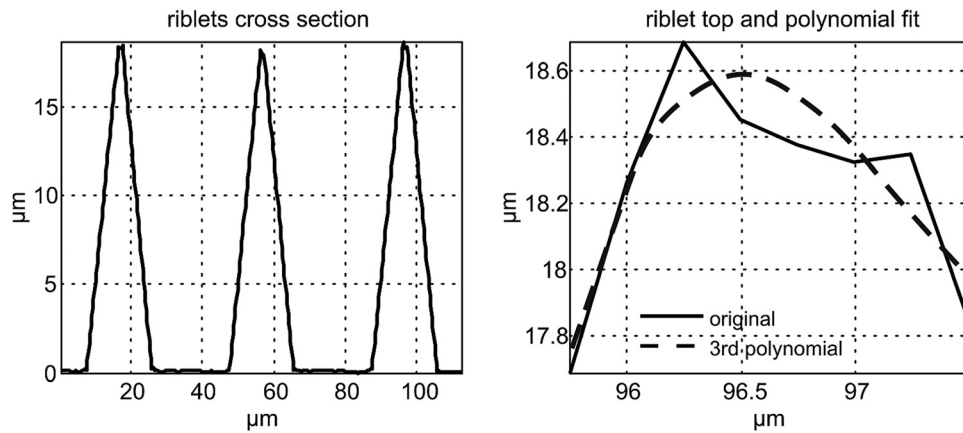


Fig. 13 Definition of the top area

Tip radii of measured surface measured with 100x lens. Mean=0.24 μm , Std. Dev.=0.07 μm Tip radii of measured surface measured with 50x lens. Mean=0.30 μm , Std. Dev.=0.08 μm

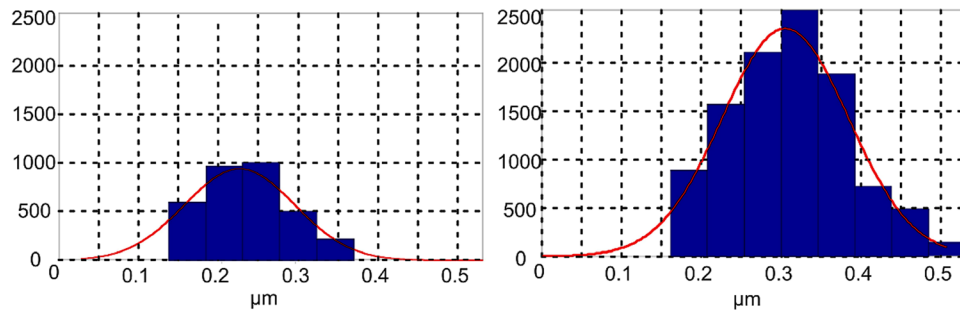


Fig. 14 Different measurement results of the same specimen

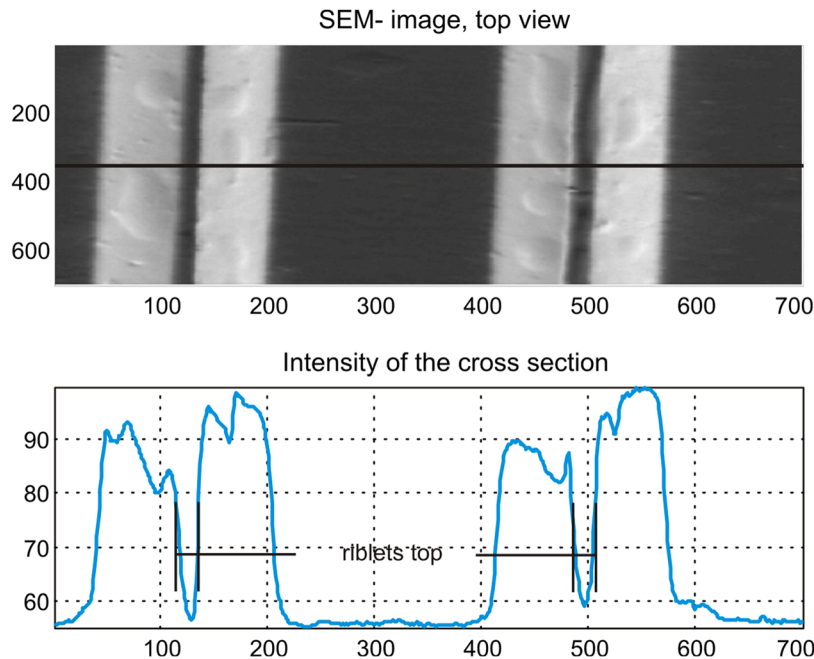


Fig. 15 Evaluation of the riblets radii using SEM

373 Aerodynamic Measurements

374 **Wall Shear-Stress Reduction.** Investigations to validate the
 375 aerodynamic effectiveness of ribs manufactured by grinding and
 376 laser structuring were carried out under ideal flow conditions in
 377 the oil channel at the Institute of Propulsion Technology of the
 378 DLR in Berlin. The main advantage of these investigations; in
 379 contrast to the investigations conducted on compressor blades in
 380 the linear cascade wind tunnel, is that the effect of the surface
 381 structures on skin friction was determined under the simplest flow
 382 conditions, using flat plates with the riblets perfectly aligned with

the main flow direction under a zero pressure gradient. Prior to the
 investigations in the oil channel, ribs were manufactured by grinding
 and laser structuring on X20Cr13 probe material in small
 scales, comparable to the size of the ribs suitable for application
 on compressor blades. Subsequently, the geometry of the manu-
 factured microstructures was measured using the optical measur-
 ing techniques described above. After postprocessing the
 measured data, the surface structures were scaled up to maintain
 Reynolds similarity for the measurements in oil. The scaled up
 riblet geometries were generated on the flat plates by rapid proto-
 typing as described in Oehlert et al [6]. More information on the
 oil channel test facility and the measurement setup is given in
 Bechert et al. [4].

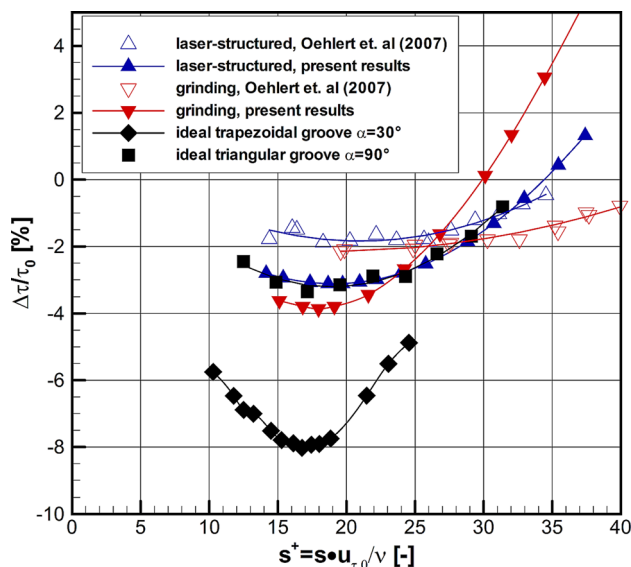


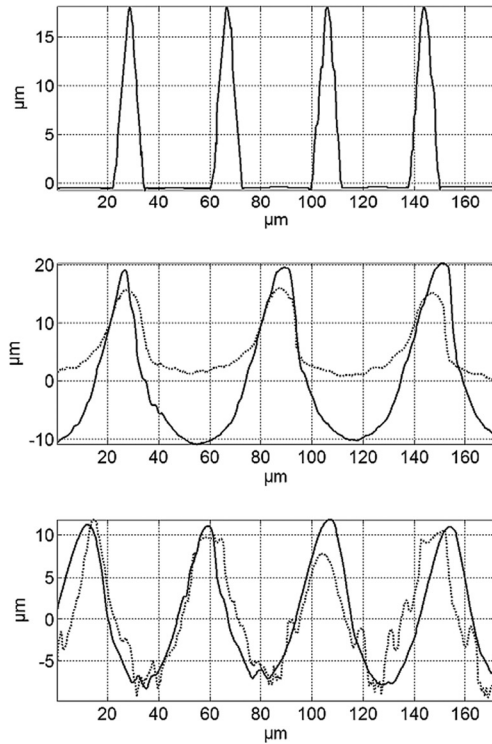
Fig. 16 Wall shear-stress reduction of ground and laser-structured riblets in comparison to riblets with an ideal shape (experimental data measured by the German Aerospace Center, Institute of Propulsion Technology, Engine Acoustics Department); curves obtained by polynomial interpolation; $\sigma = \pm 0.3\%$

Experimental results showing the influence of ground and laser-structured ribs on the relative change of wall shear-stress $\Delta\tau/\tau_0$ as a function of the dimensionless riblet-spacing s^+ in comparison to riblets with an ideal trapezoidal and triangular groove geometry obtained by Bechert et al. [4] are given in Fig. 16. The chosen target riblet geometry, characterized by a trapezoidal groove with a flank opening-angle at the tip of $\alpha = 30$ deg and a riblet height to spacing ratio of $h/s = 0.5$, is compared to the ground and laser-structured ribs of the present investigation in Fig. 17. The geometrical parameters in the evaluation of the aerodynamic effectiveness of the riblets are given in Table 2. In addition to h/s and the ratio of riblet tip diameter to riblet spacing t/s , a shape factor X is introduced to describe the triangular or the trapezoidal similarity of the groove:

$$X = \frac{A - A_{\text{triangular}}}{A_{\text{trapezoidal}} - A_{\text{triangular}}} \quad (3)$$

For $X=0$, the shape of the groove is an ideal triangle. For $X=1$ the groove has an ideal trapezoidal shape. The shape factor is calculated by the IMR during the postprocessing of the optical measurement data.

An additional increase of wall shear-stress reduction of $\Delta\tau/\tau_0 = -1\%$ is the result of improvements in the manufacturing techniques as is demonstrated by a comparison of the data presented by Oehlert et al. [6] with the result of the present investigations in Fig. 16. According to Table 2, this enhancement is



ideal trapezoidal groove

ground riblets

--- Oehlert et al. (2007)

— present results

laser-structured riblets

--- Oehlert et al. (2007)

— present results

Fig. 17 Representative cross sections of ground and laser-structured riblets in comparison to the ideal geometry with a trapezoidal groove

Table 2 Geometric parameters of ground and laser-structured ribs

Riblets	h/s	t/s	X (%)
Laser-structured [6]	0.39	0.04	10.2
Laser-structured, present results	0.39	0.04	32.5
grinding [6]	0.25	0.04	51.4
Grinding, present results	0.49	0.02	53.1

primarily due to a nearly optimal h/s of the ground ribs and an increasingly sharp riblet tip. For the laser-structured ribs, this enhancement can be related to the more trapezoidal groove geometry. Further improvements towards reducing skin friction can, thus, be achieved by an additional decrease of the tip diameter and a more trapezoidal shape of the groove geometry to even further dampen the cross flow of the streak structures at the wall.

Calculation of Wall Shear-Stress Reduction. An empirical model was developed to investigate the potential for the optimization of the grinding and laser-structuring processes. The model enables the calculation of the wall shear-stress reduction $\Delta\tau/\tau_0$ of riblets as a function of the geometrical riblet-parameters spacing s , height h , tip-radius r , and shape factor X . The model was derived by a regression analysis of the oil channel data obtained for ideal riblets by Bechert et al. [4] and Hage and Bechert [17], as well as various riblets produced by grinding and laser structuring.

Exemplary comparisons between calculated and measured wall shear-stress reduction $\Delta\tau/\tau_0$ as a function of the dimensionless riblet spacing s^+ for ideal structures and for ground and laser-structured riblets are given in Figs. 18 and 19.

In order to take into account the stochastic distributions of the ground and laser-structured ribs, probabilistic simulations were carried out using a Monte Carlo simulation (MCS). A Latin hypercube sampling (LHS) was applied to take random samples from the probability density functions of the rib geometry parameters as depicted in Fig. 20. Overall, $N = 2000$ samples were taken for the MCS. It was determined in preliminary investigations that the mean values and standard deviations of the results are independent of the sample number for $N = 2000$. Extensive calculations to validate the model, which are not shown here, were conducted on different rib structures produced by grinding and laser structuring. Overall, the experimental and calculated wall shear-stress reduction corresponds well and the validation process showed that the physical effects of the geometry parameters on wall shear-stress are well captured by the model.

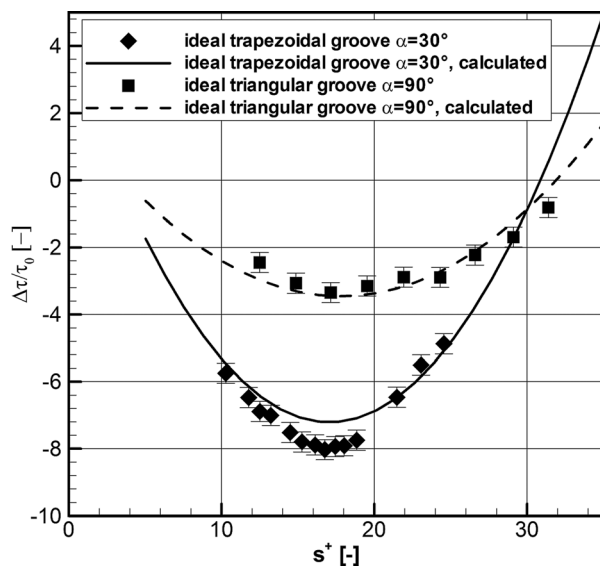


Fig. 18 Comparison of measured and calculated wall shear-stress reduction for ideal riblet; error bars indicate the standard deviation σ

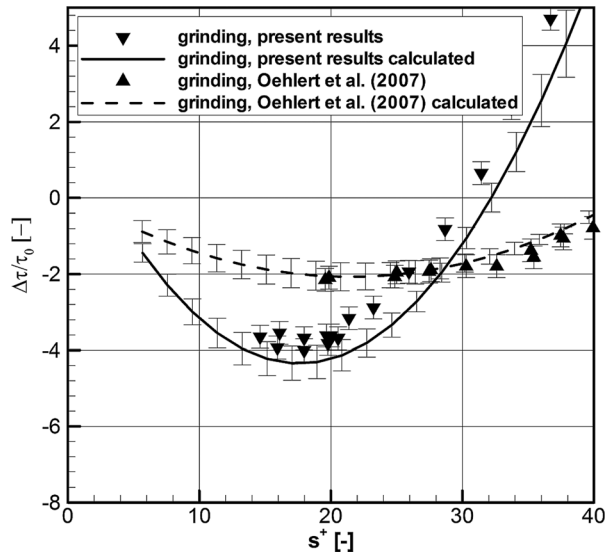


Fig. 19 Comparison of measured and calculated wall shear-stress reduction for ground and laser-structured riblets; error bars indicate the standard deviation σ

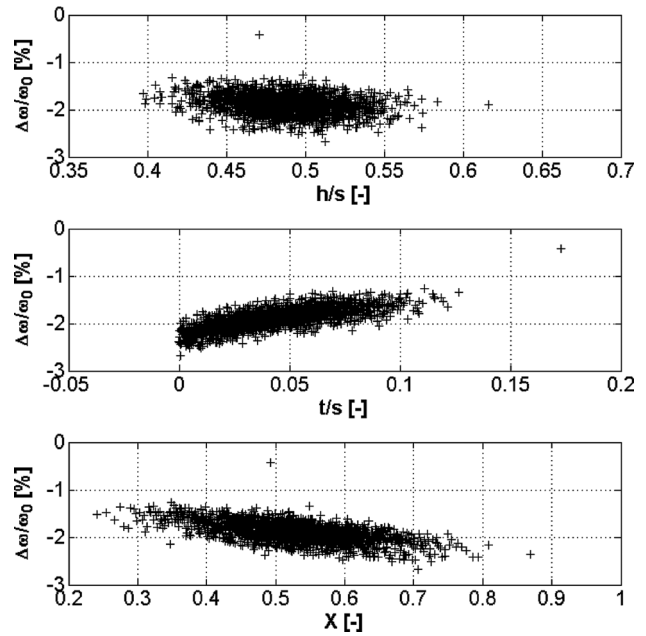


Fig. 21 Anthill plots of profile-loss reduction

455 **Probabilistic Calculations on Compressor Blades.** Numerical
 456 calculations on riblet-structured NACA 6510 compressor blades
 457 were performed using MISES, which is a viscous-inviscid cascade
 458 analysis and design system. A brief overview of the cascade flow
 459 solution method used in MISES is given by Drela and Giles [18].
 460 MISES was modified and validated in order to account for the
 461 drag-influencing effects of ideal trapezoidal groove riblets by
 462 Lietmeyer et al. [19]. To evaluate the drag-influencing effects of
 463 ground and laser-structured riblets, the model of shear-stress
 464 reduction as an empirical function of the riblet geometry
 465 described above was implemented in MISES.

466 Numerical simulations using MISES embedded in a Monte
 467 Carlo simulation were performed in order to calculate the profile-
 468 loss reduction of a blade structured by grinding. The goal of
 469 the simulations was to define further improvements in the structur-
 470 ing process. For the Latin hypercube sampling, the probability density
 471 functions of the geometrical parameters of the surface structure

were taken into account as shown in Fig. 20. The blade was struc- 472
 473 tured only on the suction side in the turbulent boundary layer
 474 downstream of a dimensionless chord length of $x/c = 0.4$. Overall,
 475 $N = 2000$ simulations were conducted using MISES. For each
 476 simulation run, the pressure loss coefficient was calculated:

$$\omega = \frac{P_{tot,1} - P_{tot,2}}{P_{tot,1} - P_{stat,1}} \quad (4)$$

To determine the effect of the riblets on the pressure loss, the dif- 477
 478 ference in the loss coefficient was calculated:

$$\frac{\Delta\omega}{\omega_0} = \frac{\omega - \omega_0}{\omega_0} \quad (5)$$

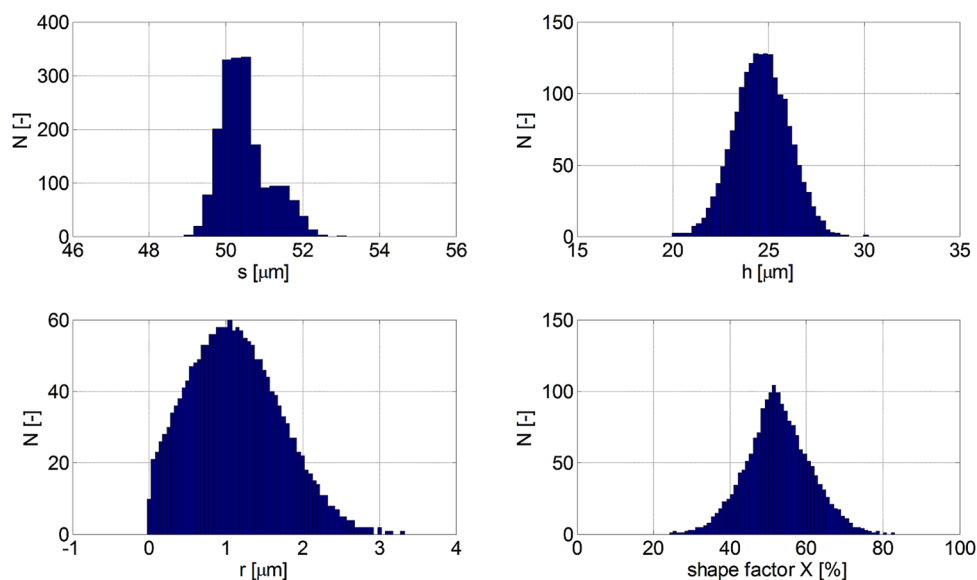


Fig. 20 Probability density functions of geometric parameters of a ground riblet structure on a NACA 6510 compressor blade (measured by IMR)

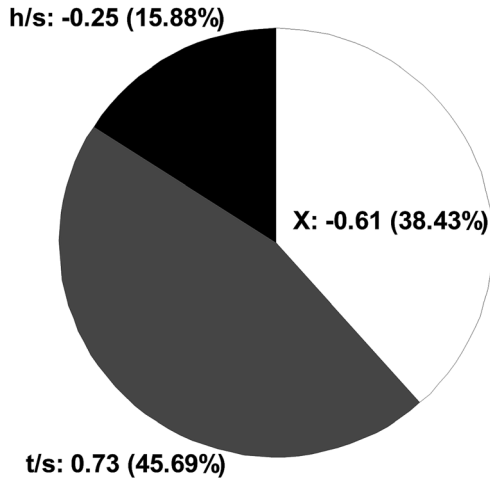


Fig. 22 Pie chart of profile-loss reduction

479 In Eq. (5) ω is the loss coefficient of the riblet-structured blade
 480 and ω_0 is the loss coefficient of the smooth reference blade. The
 481 cascade inlet flow conditions are $M=0.5$ and $Re=10^6$. Further
 482 information on the experimental setup and blade specifications is
 483 given in Ref. [9].

484 As a result of the MCS with MISES, a mean profile-loss reduction
 485 of $\Delta w/w_0 = -1.89\% \pm 0.42\%$ was calculated for the current
 486 blade structured by grinding and is in good accordance with the
 487 experimental result of $\Delta w/w_0 = -1.38\% \pm 0.29\%$. Additional
 488 conclusions from the numerical results can be drawn by plotting
 489 the profile-loss reduction ω/ω_0 over each individual realization of
 490 the MCS as depicted in Fig. 21. By applying a correlation analysis
 491 of the data, Pearson's correlation coefficient was calculated.
 492 Results of the correlation analysis are plotted in a pie-chart
 493 by normalizing each correlation coefficient by the total sum
 494 (Fig. 22). With the help of this analysis it becomes obvious that an
 495 additional reduction of profile loss can be achieved by decreasing
 496 the riblet tip diameter and by a more trapezoidal shaped groove.
 497 This supports the experimental results obtained in the oil channel
 498 presented above.

499 **Conclusions**

500 Recent advances in the manufacturing of riblets by grinding
 501 and laser structuring in relation to the geometric quality of the ribs
 502 and their aerodynamic effectiveness are presented.

503 Grinding with multiprofiled grinding wheels is an effective
 504 method for generating riblets on large-scale surfaces. With vitrified
 505 bonded grinding wheels, a reproducible aspect ratio of riblet
 506 height to spacing of $h/s=0.5$ is presently only achievable for a
 507 riblet spacing of $s > 60 \mu m$. This is the optimal aspect ratio for
 508 attaining the maximum reduction of skin friction for riblets with a
 509 trapezoidal groove, which is the target geometry. However, espe-
 510 cially near the leading edge of compressor blades under turboma-
 511 chinerylike flow conditions, the desired riblet spacing is $s < 60 \mu m$
 512 with a minimum of $s \approx 20 \mu m$. To achieve the aspect ratio of
 513 $h/s=0.5$ for such small riblet spacings, metal bonded grinding
 514 wheels were applied due to their smaller grain size. With metal
 515 bonded grinding wheels, riblets with a spacing of $s > 17 \mu m$ and
 516 an aspect ratio of $h/s=0.4$ were achieved, which is a significant
 517 improvement compared to vitrified bonded grinding wheels. A
 518 promising result is a reduction in the wear of metal bonded grind-
 519 ing wheels to 1/6 of the wear of vitrified bonded grinding wheels
 520 for a cut depth smaller than $30 \mu m$. For a cut depth greater than
 521 $30 \mu m$, the wear of metal bonded grinding wheels significantly
 522 increases. This leads to the conclusion that grinding wheels with a
 523 metal bonding are particularly suitable for the manufacturing of

small riblet geometries with a riblet height of 10 to $30 \mu m$. Vitrified
 bonded grinding wheels should be applied for the grinding of
 riblet structures with a riblet height of more than $30 \mu m$.

For the laser-structuring process, a significant decrease of
 production time was achieved by applying diffractive optical ele-
 ments. Presently, an increase in speed by a factor of five has been
 achieved using a seven-spot DOE. The variation of the rotation
 angle of the DOE during the manufacturing process provides the
 opportunity for a continuous adaption of the riblet geometry along
 the blade's surface to the local flow conditions.

To characterize the aerodynamic impact of the riblets manufac-
 tured by grinding and laser-structuring, the surface structures
 were measured with a confocal microscope and 50 times magnifi-
 cation. The measured values were confirmed with a scanning elec-
 tron microscope. The structured surface was measured in small
 patches that were stitched together in the postprocessing. Prob-
 ability density functions of riblet spacing and height were calcu-
 lated by an FFT. The probability density function of the riblet tip
 diameter was calculated by means of a third order polynomial
 approximation.

For both ground and laser-structured ribs, an additional reduc-
 tion of wall shear-stress by approximately $\Delta\tau/\tau_0 = -1\%$ was
 obtained due to improvements in the manufacturing techniques,
 which presently leads to a maximum reduction in skin friction of
 $(\Delta\tau/\tau_0)_{max} \approx -4\%$. For the ground ribs, this enhancement is
 shown to be primarily due to a nearly optimal riblet height-to-
 spacing ratio and sharper riblet tips. For the laser-structured ribs,
 this enhancement can be related to the more trapezoidal groove
 geometry. A further reduction of skin friction could, thus, be
 achieved by a further decrease of the tip diameter and a more trap-
 ezoidal shape of the groove geometry.

To assess the impact on compressor blade profile losses and in
 order to identify the potential for future optimization of the
 grinding and laser-structuring processes, an empirical model of
 wall shear-stress reduction as a function of the relevant riblet
 geometry parameters was developed. The empirical model was
 implemented in the viscous-inviscid cascade analysis code
 MISES. This combination delivers a design tool to calculate pro-
 file losses of riblet-structured linear blade cascades. Numerical
 simulations with MISES embedded in a Monte Carlo simulation
 (MCS) were performed in order to calculate the profile-loss
 reduction of a compressor blade structured by grinding. As a
 result of the MCS with MISES, a mean profile-loss reduction of
 $\Delta w/w_0 = -1.89\% \pm 0.42\%$ was calculated and is in good accord-
 ance with the experimental result of $\Delta w/w_0 = -1.38\% \pm 0.29\%$.
 By applying a correlation analysis of the data obtained by the
 MCS and a calculation of Pearson's correlation coefficient, it was
 confirmed that an additional reduction of profile loss of up to 4%
 for the investigated NACA 6510 compressor cascade can be
 achieved by decreasing the riblet tip diameter further and by a
 more trapezoidal shaped groove. This loss reduction was meas-
 ured by Ref. [9] on the compressor cascade carrying a riblet foil
 on the suction side with an ideal trapezoidal groove geometry.

577 **Acknowledgment**

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 the Institute for Turbomachinery and Fluid Dynamics (TFD), the
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592 **Nomenclature**

593	A = cross-sectional area (μm^2)
594	a_e = cut depth (μm)
595	c = chord length (mm)
596	d = diameter (μm)
597	d_g = grain size (μm)
598	d_{\min} = limited lateral resolution (nm)
599	d_{wire} = diameter of the copper wire (mm)
600	d_o = beam distance in focal plane (μm)
601	d_φ = beam distance in relation to scanning direction (μm)
602	f_{wire} = infeed of the wire (mm)
603	h = riblet height (μm)
604	h_{20} = profile height at a width of 20 μm (μm)
605	h_{60} = profile height at a width of 60 μm (μm)
606	I_{d0} = short circuit current (A)
607	L = grinding length (mm)
608	M = Mach number
609	N = number of observations
610	NA = numerical aperture
611	p = pressure (Pa)
612	r = riblet tip-radius (μm)
613	Re = Reynolds number
614	s = riblet spacing (μm)
615	t = riblet tip-diameter (μm)
616	u_τ = (skin) friction velocity (m/s)
617	v_c = cutting speed (m/s)
618	v_{cd} = cutting speed at dressing (m/s)
619	v_{ft} = feed rate (mm/min)
620	v_{fwire} = feed rate of the wire ($\mu\text{m/s}$)
621	x, y, z = wall coordinates (mm)
622	X = riblet groove shape factor
623	Δr_{swr} = radial wheel profile wear (μm)
624	Δz = lateral displacement (mm)

625 **Greek Symbols**

626	α = flank opening-angle at the riblet tip (deg)
627	φ = rotation angle (deg)
628	σ = standard deviation
629	τ = wall shear-stress (N/m^2)
630	λ = wavelength (nm)
631	ω = pressure loss coefficient

632 **Subscripts**

633	opt = optimal
634	tot = total
635	stat = static
636	0 = reference
637	+ = nondimensional, in wall coordinates

638 **Abbreviations**

639	DLR = German Aerospace Center
640	ECDD = electronic contact discharge dressing

IFW = Institute of Production Engineering and Machine Tools	641
IMR = Institute for Measurement and Automatic Control	642
LZH = Laser-Center Hannover	643
NASA = National Aeronautics and Space Administration	644
SEM = scanning electron microscope	645
TFD = Institute of Turbomachinery and Fluid Dynamics	646

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